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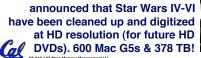
CS61C: Machine Structures

Lecture 7 – More Memory Management

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Lecturer PSOE Dan Garcia www.cs.berkeley.edu/~ddgarcia

Star Wars in HD! ⇒ **Lowry Digital Images**





Review

- C has 3 pools of memory
 - Static storage: global variable storage, basically permanent, entire program run
 - The Stack: local variable storage, parameters, return address
 - The Heap (dynamic storage): malloc() grabs space from here, free() returns it.

 Nothing to do with heap data structure!
- malloc () handles free space with freelist. Three different ways:
 - · First fit (find first one that's free)
 - · Next fit (same as first, start where ended)
 - · Best fit (finds most "snug" free space)
- One problem with all three is small fragments!

Slab Allocator

- A different approach to memory management (used in GNU libc)
- Divide blocks in to "large" and "small" by picking an arbitrary threshold size. Blocks larger than this threshold are managed with a freelist (as before).
- For small blocks, allocate blocks in sizes that are powers of 2
 - e.g., if program wants to allocate 20 bytes, actually give it 32 bytes



Slab Allocator

- Bookkeeping for small blocks is relatively easy: just use a bitmap for each range of blocks of the same size
- Allocating is easy and fast: compute the size of the block to allocate and find a free bit in the corresponding bitmap.
- Freeing is also easy and fast: figure out which slab the address belongs to and clear the corresponding bit.



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Slab Allocator

16 byte blocks:				
32 byte blocks:				
64 byte blocks:				

16 byte block bitmap: 11011000 32 byte block bitmap: 0111

64 byte block bitmap: 00

Slab Allocator Tradeoffs

- Extremely fast for small blocks.
- Slower for large blocks
 - · But presumably the program will take more time to do something with a large block so the overhead is not as critical.
- · Minimal space overhead
- No fragmentation (as we defined it before) for small blocks, but still have wasted space!



Internal vs. External Fragmentation

- With the slab allocator, difference between requested size and next power of 2 is wasted
 - e.g., if program wants to allocate 20 bytes and we give it a 32 byte block, 12 bytes are unused.
- · We also refer to this as fragmentation, but call it internal fragmentation since the wasted space is actually within an allocated block.
- External fragmentation: wasted space between allocated blocks.

Buddy System

- Yet another memory management technique (used in Linux kernel)
- Like GNU's "slab allocator", but only allocate blocks in sizes that are powers of 2 (internal fragmentation is possible)
- Keep separate free lists for each size
 - · e.g., separate free lists for 16 byte, 32 byte, 64 byte blocks, etc.



Buddy System

- If no free block of size ${\bf n}$ is available, find a block of size ${\bf 2n}$ and split it in to two blocks of size n
- When a block of size n is freed, if its neighbor of size n is also free, combine the blocks in to a single block of size 2n
 - · Buddy is block in other half larger block



Same speed advantages as slab allocator



Allocation Schemes

- So which memory management scheme (K&R, slab, buddy) is best?
 - There is no single best approach for every application.
 - Different applications have different allocation / deallocation patterns.
 - · A scheme that works well for one application may work poorly for another application.



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Administrivia

Andrew's discussion section 113 (Mon 5-6pm) will now be held in 320 Soda

Automatic Memory Management

- Dynamically allocated memory is difficult to track why not track it automatically?
- If we can keep track of what memory is in use, we can reclaim everything else.
 - · Unreachable memory is called garbage, the process of reclaiming it is called garbage collection.
- · So how do we track what is in use?



Tracking Memory Usage

- Techniques depend heavily on the programming language and rely on help from the compiler.
- Start with all pointers in global variables and local variables (root set).
- Recursively examine dynamically allocated objects we see a pointer to.
 - We can do this in constant space by reversing the pointers on the way down
- How do we recursively find pointers in dynamically allocated memory?

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Tracking Memory Usage

- Again, it depends heavily on the programming language and compiler.
- Could have only a single type of dynamically allocated object in memory
 - E.g., simple Lisp/Scheme system with only cons cells (61A's Scheme not "simple")
- Could use a *strongly typed* language (e.g., Java)
 - Don't allow conversion (casting) between arbitrary types.
 - · C/C++ are not strongly typed.

Here are 3 schemes to collect garbage

Scheme 1: Reference Counting

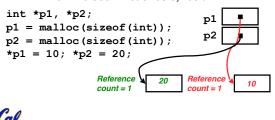
- For every chunk of dynamically allocated memory, keep a count of number of pointers that point to it.
- When the count reaches 0, reclaim.
- Simple assignment statements can result in a lot of work, since may update reference counts of many items



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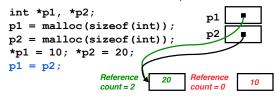
Reference Counting Example

- For every chunk of dynamically allocated memory, keep a count of number of pointers that point to it.
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Reference Counting Example

- For every chunk of dynamically allocated memory, keep a count of number of pointers that point to it.
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Reference Counting (p1, p2 are pointers)

$$p1 = p2;$$

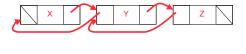
- Increment reference count for p2
- If p1 held a valid value, decrement its reference count
- If the reference count for p1 is now 0, reclaim the storage it points to.
 - If the storage pointed to by p1 held other pointers, decrement all of their reference counts, and so on...
- Must also decrement reference count
 when local variables cease to exist.

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Reference Counting Flaws

- Extra overhead added to assignments, as well as ending a block of code.
- Does not work for circular structures!
 - · E.g., doubly linked list:





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Scheme 2: Mark and Sweep Garbage Col.

- Keep allocating new memory until memory is exhausted, then try to find unused memory.
- Consider objects in heap a graph, chunks of memory (objects) are graph nodes, pointers to memory are graph edges.
 - Edge from A to B => A stores pointer to B
- Can start with the root set, perform a graph traversal, find all usable memory!
- 2 Phases: (1) Mark used nodes;(2) Sweep free ones, returning list of free nodes

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Mark and Sweep

 Graph traversal is relatively easy to implement recursively

```
void traverse(struct graph_node *node) {
   /* visit this node */
   foreach child in node->children {
       traverse(child);
   }
```

- °But with recursion, state is stored on the execution stack.
 - Garbage collection is invoked when not much memory left
- ° As before, we could traverse in constant space (by reversing pointers)

Scheme 3: Copying Garbage Collection

- Divide memory into two spaces, only one in use at any time.
- When active space is exhausted, traverse the active space, copying all objects to the other space, then make the new space active and continue.
 - · Only reachable objects are copied!
- Use "forwarding pointers" to keep consistency
 - Simple solution to avoiding having to have a table of old and new addresses, and to mark objects already copied (see bonus slides)



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Peer Instruction

- A. The Buddy System's free () is O(1), if n = the biggest "small" block (in B)
- B. Since automatic garbage collection can occur any time, it is more difficult to measure the execution time of a Java program vs. a C program.
- C. We don't have automatic garbage collection in C because of efficiency.

	ABC
1:	FFF
2:	FFT
3:	FTF
4:	FTT
5:	TFF
6:	TFT
7:	TTF
8:	TTT

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"And in Conclusion..."

- Several techniques for managing heap via malloc and free: best-, first-, next-fit
 - 2 types of memory fragmentation: internal & external; all suffer from some kind of frag.
 - Each technique has strengths and weaknesses, none is definitively best
- Automatic memory management relieves programmer from managing memory.
 - · All require help from language and compiler
 - Reference Count: not for circular structures
 - · Mark and Sweep: complicated and slow, works

Copying: Divides memory to copy good stuff

