

CS61C Fall 2012 – 6 – Midterm Review

Ackermann – Spring 2012 Midterm (Patterson)

The Ackermann function A is defined as follows:

$$A(m, n) = \begin{cases} n + 1 & \text{if } m = 0 \\ A(m - 1, 1) & \text{if } m > 0 \text{ and } n = 0 \\ A(m - 1, A(m, n - 1)) & \text{if } m > 0 \text{ and } n > 0. \end{cases}$$

Fill in the following C function so that it computes A(m, n).

```
unsigned int A(unsigned int m, unsigned int n) {
    if ( m == 0 ) {
        return n+1;
    } else if ( n == 0 ) {
        return A(m - 1, 1);
    } else {
        return A(m - 1, A(m, n-1));
    }
}
```

Now you're going to translate that C into an equivalent MIPS function. We've built a skeleton once again, but you're going to have to fill in the blanks to flesh it out.

```
A:
    addiu $sp, $sp, -12
    sw $s0, 0($sp)
    sw $s1, 4($sp)
    sw $ra, 8($sp)

    addu $s0, $a0, $0
    addu $s1, $a1, $0

    beq $s0, $0, L1

    beq $s1/$a1, $0, L2
    addu $a0, $s0, $0
    addiu $a1, $s1, -1
    jal A

    addu $a1, $v0, $0

    addiu $a0, $s0, -1
    jal A
    j Exit

L1:
    addiu $v0, $s1/$a1, 1
    j Exit

L2:
    addiu $a0, $s0, -1
    addiu $a1, $0, 1
    jal A
    j Exit

Exit:
    lw $s0, 0($sp)
    lw $s1, 4($sp)
    lw $ra, 8($sp)
    addiu $sp, $sp, 12
    jr $ra
```

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MIPS Mystery Question – Fall 2010 Midterm (Katz)

What does the assembly function `mystery` return? Write your answer as a binary number.

Address Instruction

```
0x08001000 mystery:  addiu $sp, $sp, -4
0x08001004          sw $ra, 0($sp)
0x08001008          addiu $v0, $zero, 0
0x0800100c          jal inner
0x08001010          lw $ra, 0($sp)
0x08001014          addiu $sp, $sp, 4
0x08001018          jr $ra
0x0800101c inner:   lw $v0, 4($ra)
0x08001020          jr $ra
```

001001 11101 11101 0000 0000 0000 0100

Binary encoding of `addiu $sp, $sp, 4`.

Cache Question – Fall 2011 Midterm (Garcia)

Take a look at the following C function `sum_iter` run on a 32-bit MIPS machine. On this system, these **structs** are aligned to two-word boundaries since `sizeof(struct Node) = 8`. Assume the total space taken up by the linked list is greater than (and a *multiple* of) the cache size.

```
struct Node {
    int n;
    struct Node *next;
};
int sum_iter (struct Node *head) {
    int sum = 0;
    while (head != NULL) {
        sum += head->n; // load from head+0
        head = head->next; // load from head+4
    }
    return sum;
}
```

Given a direct-mapped data cache with this configuration: **INDEX: 13 bits, OFFSET: 7 bits**

- a. How many *words* are in a block? **32 words**
b. How many *bytes of data* does this cache hold? (in IEC format) **2²⁰ = 1MiB**

Define A and B as your answers to (a) and (b) above, respectively.

For questions (c) and (d) below, use these variables in your answer if necessary.

Also, when we mention hit rate below, we're talking about accessing *data* (not instructions).

- c. What is the *lowest possible cache hit rate* for the **while** loop in `sum_iter`? **50%**
d. What is the *highest possible cache hit rate* for the **while** loop in `sum_iter`? **((A-1)/A * 100) %**
e. To achieve this maximum hit rate, we obviously could have every Node next to every other node, like an array. However, that's too strict a constraint -- we can *still* achieve this hit rate if that's not the case. What is the *loosest* constraint for how the Nodes are distributed in memory to get the best hit rate?

Nodes are laid out in memory such that when a block is kicked out, the other 15 nodes in that block will have been accessed (so a block is never kicked out without having a perfect A-1:1 hit rate). Said another way, if you draw a memory block-size wide, then all the "memory blocks" are either full or empty, and "linking" of all of them is so all nodes in a particular block has been visited before another node is visited that shares its tag (so when that block is kicked out, all nodes have been visited).