

### EE122 Fall 2012

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http://inst.eecs.berkeley.edu/~ee122/ Materials with thanks to Jennifer Rexford, Ion Stoica, Vern Paxson and other colleagues at Princeton and UC Berkeley

Announcements							

### Holy Trinity of Routing: LS, DV, PV

- · Normally presented as the complete story
- But we know how to do much better
- That is what we will talk about today.....

### **Major Routing Challenges:**

- Policy Oscillations
- Resilience
- Traffic Engineering

### Another Purpose for Today

- EE122 (CS version) is algorithmically vacuous – AIMD is the high point of intellectual depth (ugh)
- The algorithms described today are nontrivial – Algorithms simple, but their properties are nonobvious
- You will prove two results as a class exercise -5 minutes, in groups, try to come up with reasoning - I'll help shape it into a proof

### **Policy Dispute Resolution**

### **Policy Oscillations**

- Last time we discussed how BGP might never converge due to "policy oscillations"
- We now discuss how we might solve this problem

### Policy Oscillations (cont'd)

- Policy autonomy vs network stability
  - Oscillations possible with small degree of autonomy
- Focus of much recent research

### · Not an easy problem

- PSPACE-complete to decide whether given policies will eventually converge!
- However, if policies follow normal business practices, stability is guaranteed - "Gao-Rexford conditions"
  - Essentially the provider/peer/customer policy categories .

### Theoretical Results (in more detail)

- If preferences obey Gao-Rexford, BGP is safe
   Safe = guaranteed to converge
- If there is no "dispute wheel", BGP is safe -But converse is not true
- If there are two "stable states", BGP is unsafe - But converse is not true
- If domains can't lie about routes, and there is no dispute wheel, BGP is incentive compatible

### **Objectives for New Policy Approach**

- · Do not reveal any ISP policies
- Distributed, online dispute detection and resolution
- Pick "normal" path (according to policies) if no oscillation exists
  - Get something reasonable if oscillation would exist
- Account for transient oscillations, don't permanently blacklist routes























































### "Proof" of why it works · Assume that policy oscillation exists within scheme · Some router A must prefer a path offered by a router B that does not prefer that path - If everyone is getting first choice, no oscillation! - So A's first choice is B's second choice for some A.B · But router A cannot choose that path because it will have a lower precedence



### **Properties of Solution**

- · If no policy oscillation exists, get usual routes
- If policy oscillation would have existed, approach short-circuits oscillation
- If, after convergence, non-zero global precedence values exist,  $\Rightarrow$  dispute(s) exist
- · Only precedence values advertised, no other routes or policies revealed
- · Why isn't this deployed?

### Resilience

- Basic routing algorithms rely on timely consistency or global convergence to achieve ensure delivery
- -LS: routers need to have same picture of network
- DV: if algorithm hasn't converged, might loop
- · As nets grow, this gets harder and takes longer - Need both consistency/convergence and timeliness!
- · Creates lag between failure detection and recovery - Lag is biggest barrier to achieving 99.999% reliability

### Hacks Used Today

- Preconfigured backup paths
  - -When link fails, router has a backup route to use
  - Very helpful against single failures
  - Only limited protection against multiple failures
  - No systematic paradigm
- ECMP: Equal-Cost Multipath – Similar to backups, but narrower applicability
  - Choose among several "shortest-paths"

### **Solutions Presented Today**

- Multipath (one slide)
- · Failure-carrying packets
- Routing-along-DAGs

### **Multipath Routing**

### • Multipath:

- Providing more than one path for each S-D pair
  Allow *endpoints* to choose among them
- o This can be implemented by having a "path" field in packet
- · Good: if one path goes down, can use another
- Bad: Delay while endpoints detect failure (RTT)
- Absolutely necessary because of E2E arguments - But not a fundamental paradigm shift
- Part of solution, but still need more reliable routing,







### FCP Approach: Step 2

- Carry failure information in the packets! – Use this information to "fix" the local maps
- When a packet arrives and the next-hop link for the path computed with the consistent state is down, *insert failure information into packet header* – Then compute new paths assuming that link is down
- If failure persists, it will be included in next consistent picture of network
  - Then not needed in packet header





## Class Exercise: Prove This Works Develop line of argument about why this guarantees connectivity Under what circumstances does guarantee hold?

### Keys to Proof

- Deadend: as long as map plus failures has connectivity, no dead ends
- Loops: Assume loop. The nodes on the loop all share the same "consistent" map plus a set of failures in the packet header. Therefore, they compute the same path. Contradiction.

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### **Problems with FCP**

- Requires changes to packet header
   And packet headers could get long
- Requires fast recomputation of routes
   Can precompute common cases, but worst case is bad
- Does not address traffic engineering What is that?

### Traffic Engineering (TE)

- Connectivity is necessary but not sufficient
- · Need to also provide decent service
- Requires that links on the path not be overloaded
   Congestion control lowers drop rate, but need to provide reasonable bandwidth to connections by spreading load

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• TE is a way of distributing load on the network -i.e., not all packets travel the "shortest path"





- · Recover from failures without global recomputation
- Support locally adaptive traffic engineering
- Without any change in packet headers, etc.
- Or requiring major on-the-fly route recomputation

### Background

- Focus only on routing table for single destination – Could be a prefix, or a single address
  - -Routing to each destination is independent, so this is fine
- Today we compute *paths* to particular destination
   From each source to this destination there is a path

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• When path breaks, need to recompute path – The source of all our troubles!





### Load Balancing

### Use local decisions:

- Choose which outgoing links to use
- Decide how to spead the load across these links
- Push back when all outgoing links are congested o Send congestion signal on incoming links to upstream nodes
- Theorem:
  - When all traffic goes to a single destination, local load balancing leads to optimal throughput
- Simulations:
  - In general settings, local load balancing close to optimal

### **DAG-based Routing**

- Essentially a principled paradigm for backup paths - Can tolerate many failures
- Scalable
- Easy to understand and manage

### **Computing DAG**

- Use each link in a single direction
- · DAG iff link directions follow global order
- Computing a DAG for destination v is simple: – Essentially a shortest-path computation – With consistent method of breaking ties



# What about Connectivity? Multiple outgoing links improve connectivity But can RAD give "perfect" connectivity? If all outbound links fail that node is disconnected Even if underlying graph is still connected How can we fix this?

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### Link Reversal Properties

- Connectivity guaranteed!

   If graph is connected, link reversal process will restore connectivity in DAG
- This has been known in wireless literature - Now being applied to wired networks
- If you don't think this is neat, then you are asleep. – Local rule to produce ideal connectivity!

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### Keys to Proof

- Deadend: algorithm never results in dead-ends - At least one link will be outbound, if you have a link
- · Loops:
  - Assume network does not have loop at beginning o (i.e., we have a DAG)
  - Link reversal cannot create a loop
  - o Because reversed node cannot be part of a loop
  - Therefore, topology never in a state where a loop exists
- · Are we done with proof?

### No, link reversals might not terminate

- Must prove topology reaches fixed point – If underlying graph is connected
- Not reaching a fixed point means process of node reversals continues forever
- Since network is of finite size, this process must repeat in a cycle of node reversals
- How can we prove this is impossible?

### Fact #1

- If a node has a path to the destination, then it will never reverse itself.
- Conclusion: the set of nodes with a path to the destination is nondecreasing

### Fact #2

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- For a node to do a second link reversal, all of its neighbors must have also reversed its links.
- Therefore, the set of nodes doing a link reversal is an expanding set
- Can only re-reverse all reversing nodes if the process reaches the "edge" of network
- But once this process touches a node which is connected to the source, it stops. **QED.**

### Summary of RAD

- Local responses lead to:
   Guaranteed connectivity
   Close-to-optimal load balancing
- Can be used for L2 and/or L3 – No change in packet headers

### Why Isn't RAD Enough? The link reversals are on the "control plane" They take time to compute Packets can be lost in the meantime...

- Exactly the problem with FCP route recomputation Works on control-plane speeds, not data speeds
- Any suggestions?

### Data-Driven Connectivity (DDC)

- Define link reversal properties in terms of actions that can occur at data speeds
- Events: packet arriving in "reverse" direction
- Action: remove that link from outgoing set
- Goal: define simple algorithms that can be supported in HW

   Ask Panda for more details

### Review

- Major Routing Challenges:
  - Resilience
  - Traffic Engineering
    Policy Oscillations
  - Policy Oscillations
- We have solutions for all of them! – FCP, RAD, and Policy Dispute Resolution

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• Are they deployed? No..... - Will they be deployed? Maybe.....

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